Comfort 500 S

Spindle drive operator for hinged gates Installation Instructions



Overview of spindle drive unit for hinged gates (1)





Table 1: Drive unit dimensions

	а	b	С	d	е	f	g
"Standard" version	535	465	300	816	27	140	120
"Long" version	735	565	400	1016	27	140	120

Spindle drive unit Pivot - post

A B C D E F Pivot - gate wing, "open" position Pivot - gate wing, "closed" position Motor with positional sensor (speed registration) Reference point







A Electronic control unit

Voltage:	220 - 240 V, 50 Hz
Current input:	1 A max.
Power input:	0.24 kW max.
Temperature tolerance:	-30°C to +70°C
Operation:	4 min. short-term action
Motor:	Spindle unit with 36 V D.C. worm gear motor
Control voltage:	Low voltage under 24 V
Motor unit pulling and thrust power:	1000 N
Motor unit travel speed:	10.5 mm/sec
Opening time for 90°:	20 - 30 sec. depending on gate size
Travel time limit:	50 sec.
Automatic cut-out:	Programmable electronic power limit, separately adjustable for both operational directions.
Final cut-off:	Electronic, through microprocessor, with incremental hodometry (path measuring system)
Emergency release: Total weight	With release mechanism in the gate wing mounting bracket
(single-wing version): Total weight	12 kg
(double-wing version):	18 kg
Safety type motor:	IP 44
Safety type control unit:	IP 65



Fixing the pivot points, fitting the bracket to the post and gate wing



- A B Stop plates with lock Gate wing
- С Gate post
- D Spindle drive unit
- Е Control unit F junction box

Ē



Fixing the pivot points



* Distance ",c" for LH hinging (drive operator on left gate wing): drill hole 1 * Distance ",c" for RH hinging (drive operator on right gate wing): drill hole 2



"Standard" version



"Long" version

- On-site building-in depth e =
- A B Post mounting bracket
- Release box on the gate wing



Installing the fittings

Post mounting bracket

In order to ensure an opening angle of 90 degrees, the addition of measurements a + b should roughly correspond to the spindle stroke.

a + b = 225 ... 285 mm for the "standard" version

 $a + b = 240 \dots 380 \text{ mm}$ for the "long" version

For larger gate wings, the full working stroke should be used in order to limit the gate speed of the wing outer edges. Anchor the post mounting bracket in the masonry (see fig. 3c).

Building-in dimensions are specified in tables 2 + 3.

If the on-site maximum building-in measurement "e max" exceeds the specified values, then the drive operator must be set into the masonry with the mounting bracket.

Insert the hinged gate drive operator into the corresponding drill hole of the post mounting bracket and screw tight with an M10 hexagon nut.

Table 2: If the building-in dim. is less than 40 mm, use the "standard" version of the spindle drive operator										
Preferred dimensions for gate wing width <2000			Preferred dimensions for gate wing width >2000			Preferred dimensions for largest possible opening angle				
Building-in			Opening	Opening		Opening	Opening		Max. Opening	Opening
dim. e	а	b	angle	time	b max.	angle	time	b min.	angle	time
mm	mm	mm	degrees	sec.	mm	degrees	sec.	mm	degrees	sec.
less than 0	125	100	90°	16	160	90°	21	140	110°	22
0 - 20	135	100	90°	18,5	140	90°	21	120	105°	22
20 - 40	155	100	90°	20	115	90°	21	115	100°	22

Table 3: Building-in dim. e = 40 200 mm. Use the "long" version of the spindle drive operator										
Preferred dimensions for gate wing width <2000		ions for <2000	Preferred dimensions for gate wing width >2000			Preferred dimensions for largest possible opening angle				
Building-in			Opening	Opening		Opening	Opening		Max. Opening	Opening
dim. e	а	b	angle	time	b max.	angle	time	b min.	angle	time
mm	mm	mm	degrees	sec.	mm	degrees	sec.	mm	degrees	sec.
40 - 60	140	100	90°	18,5	240	90°	28	180	120°	29
60 - 80	160	100	90°	19,5	220	90°	28	180	115°	29
80 - 100	180	100	90°	21,5	200	90°	28	160	110°	29
100 - 120	200	100	90°	22	180	90°	29	160	100°	29
120 - 140	220	100	90°	24	160	90°	29	140	100°	29
140 - 160	240	100	90°	26	140	90°	29	120	100°	29
160 - 180	260	100	90°	28	120	90°	29	100	95°	29
180 - 200	280	100	90°	29	100	90°	29	100	90°	29

Release box

(for single-wing version, this may have to be reversed, depending on which side the gate is hinged)



Fitting the release box to the gate wing

To establish the fixing points on the gate wing:

With the spindle fully extended, connect the hinged gate operator in alignment with the release box and mark the position. Open the release box and drill 2 holes centrally within the elongated holes (6 mm dia. drill). Make the release box and the drive operator secure, then make a test run. Carry out any necessary fine adjustment via the elongated holes.

Remove rotary latch. Drill the outer hole and then screw the centrally located screw into this drill hole. This will prevent the box from sliding sideways. Push rotary latch back in again. Place on washer and tighten hexagon nut until rotary latch is sluggish to operate.





Secure the control unit to the post using wall plugs and screws, then plug into mains and make a test run. On completing the test run, remove the mains lead with plug and have the control unit properly connected to the electricity supply by a qualified electrician.

- Mains lead 240 V 50 Hz (e.g. NYY 3 x 1.5 on site by the customer) а
- b Connecting cable for motor (by the factory)
- Connecting cable for motor (by the factory or NYY 0 9 x 1.5 with junction box on site by the customer) c d
- Control cable for push button, key switch (e.g. NYY 0 6 x 1.5 on site by the customer).
- * If the control unit cannot be installed near the gate, please request a corresponding cable layout plan.

Overview of control unit 500; single- and double-wing versions



Display А

(5)

- В LED
- С Power limit "open"
- Power limit "close" D
- Test button "open" Test button "close" Е
- F
- G Programming button
- Н Plug-in connection transformer 220 V
- Mains fuse F1, 1A max. Т
- J Motor fuse F2 4A max. Κ LED motor voltage
- L
- Socket for on-site lighting Plug-in connection control panel Μ
- LED socket Ν
- 0 Plug-in terminal X2a mains voltage
- Ρ Plug-in terminal X2e motor connection gate wing 1
- Q Plug-in terminal X2d motor connection gate wing 2
- Switches S 18, S 20 R
- System socket for electronic aerial S
- System socket X5 open close stop Т
- U Plug-in terminal X2d open - close gate wing 1
- Plug-in terminal X2f photocell 24 V V
- W Plug-in terminal X2e open - close - stop
- Х Change-over switch S23: A = single-wing version



Control 500 connecting plan; single- and double-wing versions





Control 500 circuit diagram; single- and double-wing versions



- F1 Fuse 1A max
- F2 Fuse 4A max Η4
- LED reference point
- On-site lighting (250V,60W max) H20
- К1 Relay "open" gate wing 1 К2
- Relay "close" gate wing 1 Relay "open" gate wing 2 Relay "close" gate wing 2 K3
- Κ4
- К5 Relay magnetic lock
- К6 Relay light
- K11 Magnetic lock gate wing 1*
- Magnetic lock gate wing 2* K12
- ΚL Photocell
- M1 Motor 36V DC, gate wing 1
- M2 Motor 36V DC, gate wing 2 (only w.2-wg.vers.)
- Main switch or button "Emergency off" S
- SO "Stop" button
- S1 "Impulse" button gate wing 1 & gate wing 2*
- "Open" button gate wing 1 & gate wing 2* "Close" button gate wing 1 and gate wing 2* S2
- S4
- S5 "Impulse" button gate wing 1

- Programmingbutton 2nd "stop" button S18
- S20 Programmingbutton photocell
- S21 Reed contact reference point (bistable) gate wing 1
- S22 Reed contact reference point (bistable gate wing 2
- S23 Change-over switch single- and two-wing version
- Socket for external control elements ST1
- Electronic aerial ST2
- T1 Transformer
- X1 Safety electric socket
- X1a Safety plug
- X2a Socket mains connection
- X2b Socket for on-site lighting
- X2c Socket motor connection gate wing 1
- X2d Socket motor connection gate wing 2
- X2e Socket connection button open, stop, close
- X2f Socket connection "impulse" button gate wing 1
- Socket connection photocell X2g
- X4 Socket "electronic aerial"
- X5 Socket connection button open, stop, close

* if installed

On connecting, remove bridge or ensure programming button a OFF.

Caution! Low voltage!

External voltage at the terminals will completely destroy the electronics.

Important: Observe local safety regulations!

Always lay mains cable and control cable separately.

Control voltage 24V DC Motor voltage 40V DC

Factory-bridged terminals, coding switch							
Description	Terminal block	Bridged terminals	Programming button				
"Stop" button "Stop" button Photocell "Impulse" button	X2 ST1 KL X2e	12-13 - - a	- 518 520 -				



- A Battery transmission control light
- B Operating buttons
- C Battery cover
- D Battery 3V CR 2032
- E Coding plug
- Please open the cover to change or insert the battery. Observe right poling when changing the battery.



Attention!

Only operate the hand transmitter after you have made sure that there are neither persons nor objects in the operating range of the door.



Attention!

- Children are not allowed to play with hand transmitters! - Batteries are excluded from warranty.





8 Module aerial



Plug electronic aerial into the control unit (socket ST2) as shown in fig. 5, point "S". The range may vary with different digital security codings.

- A Module aerial
- B Connecting lead with plug

(9)

Adjustment and coding

9a

Putting into operation

Switch on at the mains. LED \ominus lights up. After pressing the test buttons 4 d, the gate first moves in the direction of the reference point.

If the drive unit is not installed, the swivel joint (fig 1 "C" must be held in a vertical position).

Important: The limit stop is pre-set at the factory.

The power limit can now be set in accordance with fig. 9c.

Proceed with programming the remote control as illustrated in fig. 9d.

Press the \overline{A} button to bring the gate into the final "open" position, then proceed with programming the final positions in accordance with figs 9g/9h/9i. The programming procedure terminates automatically 30 seconds after the last entry, or can be terminated manually by pressing the "P" button (see figs. 9d/9e/9f/9g/9h and 9i).







9c Setting the power limits

Press the $\stackrel{\frown}{\square}$ button to set the power limit "open", and press the $\stackrel{\frown}{\square}$ button to set the power limit "close". The set value will be displayed.

By repeatedly pressing the appropriate button, the power limit can be set in stages from 0 (most sensitive value) to 19 (pre-set value = 9).

Attention: To protect persons as well as the mechanical parts of the door and operator, set the power limit as sensitively as possible - on no account exeed 150 N (approx. 15 kg.)



The power limits are now set.



Coding the receiver for single-wing version (only with electronic aerial)

Press button "P" for 2 seconds "F" is displayed LED $\widehat{\frown}$ lights up LED \bigoplus flashes



Multi-channel hand transmitter: Press any button.



Display "-" Receiver coding is stored (only with electronic aerial)





Programming is completed.



Programming is completed.



Programming the receiver for the double-wing version - gate 1 only

(only with multi-channel hand transmitter, e.g. button "B" with two-wing version and with electronic aerial)



Programming is completed.



Setting the limit stops for single-wing version (gate must be in "OPEN" position)

Press button "P" for 2 seconds "F" is displayed LED 🗢 lights up LED Θ flashes



LED 🖒 flashes

Press the Σ button and keep it depressed until the gate has reached the final "close" position.

Fine adjustment can be made by briefly pressing button 4 or button 4 which increases or reduces the travel distance of the gate by approx. 4 mm, without the gate moving!

The final "close" position (limit stop) is stored. Press the $\frac{1}{4}$ button and keep it depressed until the gate has reached the final "open" position.

Make fine adjustment as described above.

The final "open" position (limit stop) is stored.





"CLOSE" direction 00000 Ð Press button "P" only with autom. timed return 00000 00000 Ţ В (0)



Programming is completed.



Setting the limit stops for the double-wing version - gate 1 (gate must be in "OPEN" position)



"E" is displayed

Q Ç \bigcirc \cap \mathbb{C}

LED (flashes

Press button \checkmark and keep it depressed until the gate has reached the final "CLOSE" position.

Fine adjustment an be made by briefly pressing button 1/2 or button 4/2 which increases or reduces the travel distance of the gate by approx. 4 mm, without the gate moving!

The final "CLOSE" position (limit stop) is stored. Press button \overline{A} and keep it depressed until the gate has reached the final "OPEN" position.

Carry out fine adjustment as described above.

The final "OPEN" position (limit stop) is stored.



Programming is completed.



Setting the limit stops for the double-wing version - gate 2

Press button "P" for 2 seconds "F" is displayed LED 🔶 lights up LED \ominus flashes



LED (flashes

Press button \checkmark and keep it depressed until the gate has reached the final "CLOSE" position.

Fine adjustment can be made by briefly pressing button $\frac{1}{2}$ or button $\frac{3}{4}$ which increases or reduces the travel distance of the gate by approx. 4 mm, without the gate moving!

The final "CLQSE" position (limit stop) is stored. Press button $\stackrel{\frown}{A}$ and keep it depressed until the gate has reached the final "OPEN" position.

Carry out fine adjustment as described above.

The final "OPEN" position (limit stop) is stored.

"OPEN" direction

"CLOSE" direction



9j

Setting the time-delayed start for the double-wing version

Press button "P" for 2 seconds "F" is displayed LED 중 lights up LED ⊖ flashes



Display	Time delay
0	0.5 sec.
1	1.0 sec.
2	2.0 sec.
3	3.0 sec.
4	4.0 sec.
5	5.0 sec.
6	6.0 sec.
7	7.0 sec.
8	8.0 sec.
9	9.0 sec.
10	10.0 sec.
11	11.0 sec.
12	12.0 sec.
13	13.0 sec.
14	14.0 sec.
15	15.0 sec.
16	16.0 sec.
17	17.0 sec.
18	18.0 sec.
19	19.0 sec.

"H" is displayed

To program the time-delayed start, press button $\stackrel{\frown}{\bigsqcup}$. The set value is displayed. By repeatedly pressing the button, the time delay can be set in stages from 0 to 19 (pre-set value = 2).





Programming the type of operation

5	-B55	Impulse/stop/impulse in opposite direction
6	-B5/B6	Open/close with self-hold
7	-B5/B6	Open/close with self-hold and autom.timed return
8	-B5/B6	Open/close with self-hold and autom.timed return after driving past the site photocell

B55/B5/B6, B5/B6 with autom. timed return (pre-programmed at the factory for sequential phase control B55 - do not alter unless necessary).

Programming

Press button $\stackrel{\bullet}{\square}$ while switching the unit on.

Select with button , and store selected setting with button "P" (after 30 seconds storage is automatic).

Display 7 or 8:

Setting the "prewarning" or "gate open time" in accordance with fig. 9j.

Connection of red traffic light H20 to terminal 1 and N (X2b as per fig. 6b)



(91)

Programming the light relay K6

Indicator/Display for operating mode 2 to 6

- 1 3-minute light phase
- 2 Flashing impulse
- 3 Gate operation
- -----

Indicator/Display for operating mode 7, 8, 9

- 2 Flashing light
- 3 Revolving beacon

(pre-set at the factory for 3-minute light phase, do not alter unless necessary).

Programming

Press button $\stackrel{\checkmark}{{}}$ while switching the unit on.

Select with button and store selected setting by pressing button "P" (after 30 seconds storage is automatic).

If the self-hold function has been programmed on display 7 or 8, programming the light relay will be ineffective.

Connect up site lighting, flashing light or beacon in accordance with the circuit diagram.

Function messages			Fault messages
Display	Function	Display	Display Fault
0 2	Stop button Impulse OPEN (hutton/remote control)	8 9	Reference contact without function motor 1 / Hybrid photocell (RPM detecter) w/out function motor 1
4	Impulse CLOSE (button/remote control)	10	Power limit motor 1
6 7	Driveway photocell Programming aborted	11 16 17 18 19	Operation time limitn Power limit self-monitering not o.k. Reference contact without function motor 2 Hybrid photocell (RPM detecter) w/out function motor 2 Power limit motor 2



Cancelling the settings

Press button "P" while switching the unit on. "c" appears in the display.



Setting the automatic timed return (only with operation types 7 and 8 in accordance with fig. 9j)

Press button "P" for 2 seconds "F" is displayed LED 😤 lights up LED \ominus flashes



Display	Open time	Prewarning time
0	5 sek.	2 sek.
1	10 sek.	4 sek.
2	15 sek.	6 sek.
3	20 sek.	8 sek.
4	25 sek.	10 sek.
5	30 sek.	12 sek.
6	35 sek.	14 sek.
7	40 sek.	16 sek.
8	50 sek.	18 sek.
9	60 sek.	20 sek.
10	80 sek.	22 sek.
11	100 sek.	24 sek.
12	120 sek.	26 sek.
13	150 sek.	28 sek.
14	180 sek.	30 sek.
15	255 sek.	32 sek.

Press button "P" again until "A" appears in the display.





00000 ₽ ⊕ ŀ [} \Box Prewarning time

Open time

Press button $\stackrel{\frown}{\Box}$ or button $\stackrel{\frown}{\Box}$ - selected setting is displayed. By repeatedly pressing the appropriate button, the "open time" and the "prewarning time" can be set in stages from 0 to 15. (pre-set value = 1).

Press button "P"



Programming is completed.

Disengaging the drive operator in the event of a power failure





a) Release from the inside

Turn rotary latch (B) around 90°. The release box (A) opens. The gate can then be operated manually.

 Release from the outside (not part of the supply package)
Insert the key, turn 180 degrees clockwise and withdraw the key with the inner cylinder until the release box opens. The gate can then be opened manually.

Important: Before resuming power-operation, allow the gate to latch into the release box manually and lock.

It is advisable to test the release mechanism from time to time to ensure it is in good working order.

- Note: After actuating the release, the gate can be fully opened in the closed position but cannot be closed in the open position. In this instance, the drive operator must be unscrewed from the gate.
- A Release box
- B Rotary latch
- C Location piece
- D Location hole for shackle-type lock (not part of the supply package) to secure the rotary latch.

Fitting the electr. lock (optional accessory - to be used for gate wings wider than 2000 mm) Electr. lock on single-wing hinged gate (electr. gate post lock,



code no. 564 512, required)

Screw mounting plate (B) to gate wing and fit electr. lock (A). Secure striking plate (E) to the post. Wire the electr. lock in accordance with the circuit diagram.



11c

Electr. lock on each wing of a double-wing gate construction (2 x electr. ground locks, code no. 564 509 and - if not provided - stop plate with opening to accept electr. lock bolt, code no. 564 518, required).

Screw mounting plate (B) to gate wing and fit electr. lock (A). Attach stop plate (C). Wire electr. lock in accordance with the circuit diagram.



Electr. lock on double-wing hinged gate construction with stop bars (electr. ground lock, code no. 564 509 and - if not provided - stop plate with recess to accept bolt of electric lock, code no. 564 518, required).





Screw mounting plate (B) to gate wing and fit electr. lock (A). Attach stop plate (C). Wire electr. lock in accordance with the circuit diagram.

- A Electr. lock
- B Mounting plate C Stop plate
- C Stop plate D Locking cylinder
- E Striking plate



Test Instructions (only for the specialist!) Trouble shooting:

Fault	Cause	Remedy	
No green light on operation lamp.	No voltage.	Check mains supply. Check mains fuse F1.	
	Thermal protection is activated.	Allow trafo to cool down.	
Fault indicator flashing "red". display 10 or 19	Automatic cut-out set too sensitively. Door operation too sluggish. Door blocks.	Adjust automatic cut-out to be less sensitive as per fig. 9c. Ensure door moves easily.	
Display 9 or 18 Drive operates withaot self-hold.	Positional sensor is defective.	Replace positional sensor in motor.	
No function.	Defective electronics.	Disconnect drive unit from the mains. Remove electronic circuit boards and have them tested.	
No reaction on impulse.	"impulse" button bridged, e.g. due to short-circuit or wrong terminal connection.	Tempo ravily solate wired key switches or push buttons to trace wiring fault.	



